

EEE 324 Digital Signal Processing

Lectures 13, 14 Frequency Response for Rational System Functions

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Contents

• Frequency Response for Rational System Functions



• If a stable LTI system has a rational system function, then its frequency response has the form

$$H(e^{j\omega}) = \frac{\sum_{k=0}^{M} b_k e^{-j\omega k}}{\sum_{k=0}^{N} a_k e^{-j\omega k}}$$

• Substituting $z = e^{j\omega}$ in Eq. (13), $H(e^{j\omega}) = \left(\frac{b_0}{a_0}\right) \frac{\prod_{k=1}^{M} (1 - c_k e^{-j\omega})}{\prod_{k=1}^{N} (1 - d_k e^{-j\omega})}$ (15) $|H(e^{j\omega})| = \left|\frac{b_0}{a_0}\right| \frac{\prod_{k=1}^{M} |(1 - c_k e^{-j\omega})|}{\prod_{k=1}^{N} |(1 - d_k e^{-j\omega})|}$ (15a)

•
$$|H(e^{j\omega})| = \frac{(product of the magnitudes of all the zero factors of H(z) evaluated on the unit circle)}{(product of the magnitudes of all the pole factors evaluated on the unit circle)}$$



• Sometimes, it is convenient to consider magnitude squared of the system function.

$$\left| H(e^{j\omega}) \right|^{2} = H(e^{j\omega}) H^{*}(e^{j\omega})$$
(15b)
$$\left| H(e^{j\omega}) \right|^{2} = \left(\frac{b_{0}}{a_{0}}\right)^{2} \frac{\prod_{k=1}^{M} (1 - c_{k}e^{-j\omega})(1 - c_{k}^{*}e^{-j\omega})}{\prod_{k=1}^{N} (1 - d_{k}e^{-j\omega})(1 - d_{k}^{*}e^{-j\omega})}$$
(15c)



Log Magnitude Representation of Frequency Response

• The log of Eq. (15a) is:

 $20\log_{10}|H(e^{j\omega})| = 20\log_{10}\left|\frac{b_0}{a_0}\right| + \sum_{k=1}^M 20\log_{10}\left|(1 - c_k e^{-j\omega})\right| - \sum_{k=1}^N 20\log_{10}\left|(1 - d_k e^{-j\omega})\right|$ (15d)

- The function $20 \log_{10} |H(e^{j\omega})|$ is known as the *log magnitude* of $H(e^{j\omega})$ and is expressed in decibels (dB).
- It is also known as the *gain in dB* i.e.,

$$\begin{aligned} Gain \ in \ dB &= 20 \log_{10} |H(e^{j\omega})| \\ 0 \ dB \Rightarrow |H(e^{j\omega})| &= 1 \\ |H(e^{j\omega})| &= 10^m = 20m \ dB \\ |H(e^{j\omega})| &= 2^m \cong 6m \ dB \\ |H(e^{j\omega})| &< 1 \Rightarrow 20 \log_{10} |H(e^{j\omega})| < 0 \end{aligned}$$



Log Magnitude Representation of Frequency Response Attenuation in $dB = -20 \log_{10} |H(e^{j\omega})|$ = -Gain in dB

Advantage 1:

• The attenuation is a positive number when the magnitude response is less than unity. e.g., 60 *dB* attenuation $\Rightarrow |H(e^{j\omega})| = 0.001$



Log Magnitude Representation of Frequency Response

Advantage 2:

• From Eq. (3a),

 $20\log_{10}|Y(e^{j\omega})| = 20\log_{10}|H(e^{j\omega})| + 20\log_{10}|X(e^{j\omega})|$ (16)

- The frequency response in dB is added to the log magnitude of the i/p FT to find the log magnitude of the o/p FT.
- The effects of both magnitude and phase are additive.



Phase Response for RSF

- The phase response for a rational system function has the form $\angle H(e^{j\omega}) = \angle \left[\frac{b_0}{a_0}\right] + \sum_{k=1}^{M} \angle \left[1 - c_k e^{-j\omega}\right] - \sum_{k=1}^{N} \angle \left[1 - d_k e^{-j\omega}\right] \quad (17)$
- As in Eq. (15d), the zero factors contribute with a plus sign and the pole factors contribute with a negative sign.



Group Delay for RSF

- The corresponding group delay for a rational system function has the form $grd[H(e^{j\omega})] = \sum_{k=1}^{N} \frac{d}{d\omega} \left(arg[1 d_k e^{-j\omega}] \right) \sum_{k=1}^{M} \frac{d}{d\omega} \left(arg[1 c_k e^{-j\omega}] \right)$ (18)
- Here arg[] represents the continuous phase. Equivalently,

$$grd[H(e^{j\omega})] = \sum_{k=1}^{N} \frac{|d_k|^2 - Re\{d_k e^{-j\omega}\}}{1 + |d_k|^2 - 2Re\{d_k e^{-j\omega}\}} - \sum_{k=1}^{M} \frac{|c_k|^2 - Re\{c_k e^{-j\omega}\}}{1 + |c_k|^2 - 2Re\{c_k e^{-j\omega}\}}$$
(18a)

- In Eq. (17), the phase is ambiguous
 - Any integer multiple of 2π can be added to each term at each value of ω without changing the overall value of the complex number.
- The expression for group delay in Eq. (18) involves differentiating the continuous phase.



<u>Phase Response for RSF (In terms of the principal value)</u>

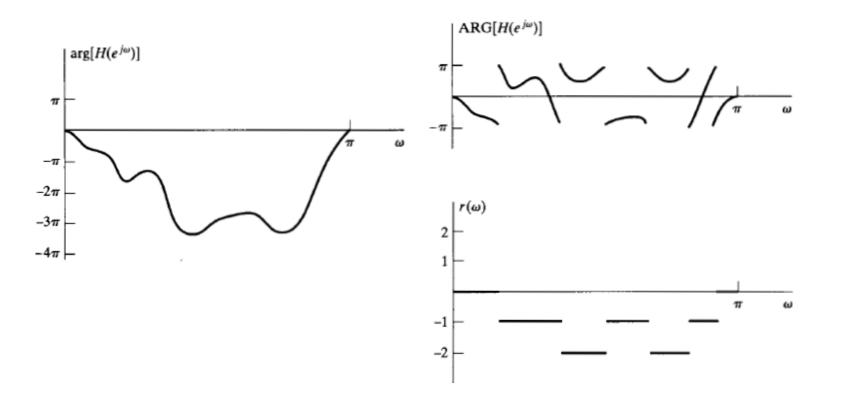
- When the angle of a complex number is calculated using a calculator, the principal value is obtained.
- The principal value of the phase of $H(e^{j\omega})$ is denoted as $ARG[H(e^{j\omega})]$, where $-\pi < ARG[H(e^{j\omega})] \le \pi$
- The correct complex value of the function $H(e^{j\omega})$ in terms of the principal value is:

angle
$$(H(e^{j\omega})) = ARG[H(e^{j\omega})] + 2\pi r(\omega)$$

Where $r(\omega)$ can be a positive or a negative integer which can be different at each value of ω .



<u>Phase Response for RSF (In terms of the principal value)</u>



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$\frac{Phase \ Response \ for \ RSF}{ARG[H(e^{j\omega})]} = \\ARG\left[\frac{b_0}{a_0}\right] + \sum_{k=1}^{M} ARG\left[1 - c_k e^{-j\omega}\right] - \sum_{k=1}^{N} ARG\left[1 - d_k e^{-j\omega}\right] + 2\pi r(\omega)$

• In general, the principal value of a sum of angles is not equal to the sum of the principal values of the individual angles.

Also,

$$ARG[H(e^{j\omega})] = \arctan\left[\frac{H_{I}(e^{j\omega})}{H_{R}(e^{j\omega})}\right]$$
$$H_{R}(e^{j\omega}): Real Part of H(e^{j\omega})$$
$$H_{I}(e^{j\omega}): Imaginary Part of H(e^{j\omega})$$



(19)

$\begin{array}{l} \hline Group \ Delay \ for \ RSF \ (In \ terms \ of \ the \ principal \ value) \\ grd[H(e^{j\omega})] = -\frac{d}{d\omega} \{\arg[H(e^{j\omega})]\} \\ \bullet \ \text{Except at discontinuities of } ARG[H(e^{j\omega})], \\ \frac{d}{d\omega} \{\arg[H(e^{j\omega})]\} = \frac{d}{d\omega} \{\operatorname{ARG}[H(e^{j\omega})]\} \end{array}$

• Hence, group delay can be obtained from the principle value by differentiating, except at discontinuities.



Practice Problems

Problems 5.1 – 5.15, 5.17, 5.19, 5.35, 5.36 (Oppenheim)

