



COMSATS Institute of
Information Technology

EEE 324 Digital Signal Processing

Lecture 5

Up-sampling

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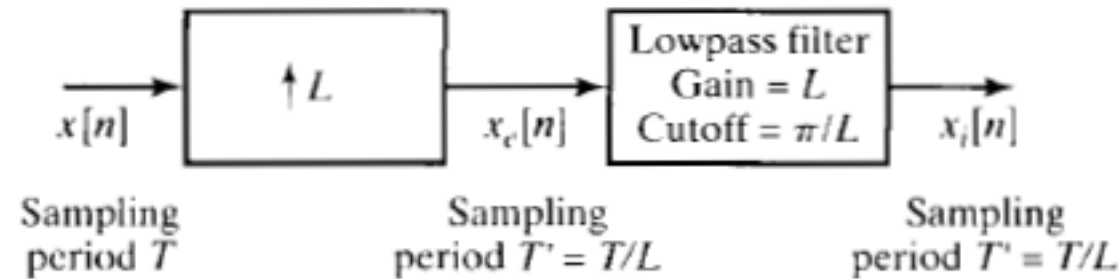
- The objective is to obtain samples $x_i[n] = x_c(nT')$ from the sequence of samples $x[n] = x_c(nT)$ where $T' = T/L$ where L is a positive integer.
- The operation of increasing the sampling rate is called *upsampling*.

$$x_i[n] = x \left[\frac{n}{L} \right] = x_c \left(n \frac{T}{L} \right), \quad n = 0, \pm L, \pm 2L \dots$$

Up-Sampling (Increasing the Sampling Rate)

Frequency Domain Representation of Up-Sampling

- A general system for up-sampling by a factor of L is shown below.



- The system on the left: Expander (or Sampling rate expander)

$$x_e[n] = \begin{cases} x\left[\frac{n}{L}\right], & n = kL, \quad k \in Z \\ 0, & \text{else} \end{cases}$$

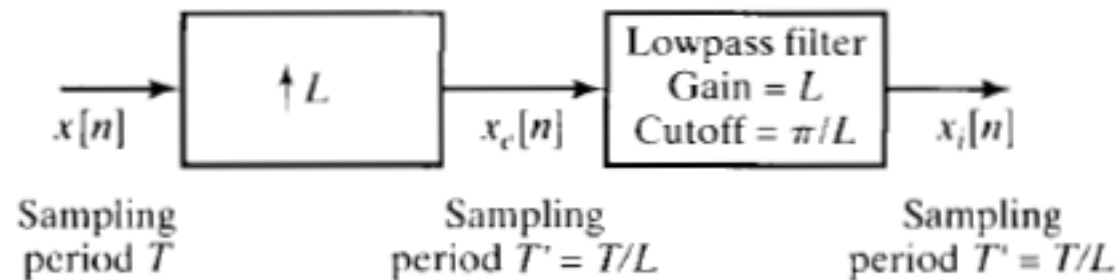
Equivalently,

$$x_e[n] = \sum_{k=-\infty}^{\infty} x[k] \delta[n - kL] \quad (38a)$$

Up-Sampling (Increasing the Sampling Rate)

Frequency Domain Representation of Up-Sampling

- A general system for up-sampling by a factor of L is shown below.



- The system on the right: DT LPF with COF = π/L and gain L
- Such a system is called an *interpolator*, and
- Up-sampling is therefore considered as *interpolation*.

Up-Sampling (Increasing the Sampling Rate)

Frequency Domain Representation of Up-Sampling

- Taking the DTFT of Eq. (38a),

$$X_e(e^{j\omega}) = \sum_{n=-\infty}^{\infty} \left(\sum_{k=-\infty}^{\infty} x[k] \delta[n - kL] \right) e^{j\omega n} \quad (39)$$

$$X_e(e^{j\omega}) = X(e^{j\omega L}) \quad (40)$$

- Up-sampling contracts the DTFT by a factor of L .
- This can cause aliasing in high frequencies.
- To remove aliasing, we can low-pass filter $x_e[n]$, by applying an ideal low-pass filter

$$H_e(e^{j\omega}) = \begin{cases} L, & |\omega| < \pi/L \\ 0, & \frac{\pi}{L} \leq |\omega| \leq \pi \end{cases}$$

Up-Sampling (Increasing the Sampling Rate)

Frequency Domain Representation of Up-Sampling

$$\Omega_S = 2\Omega_N$$

$$\Omega_N = \frac{1}{2}\Omega_S$$

$$\omega_N = \pi$$

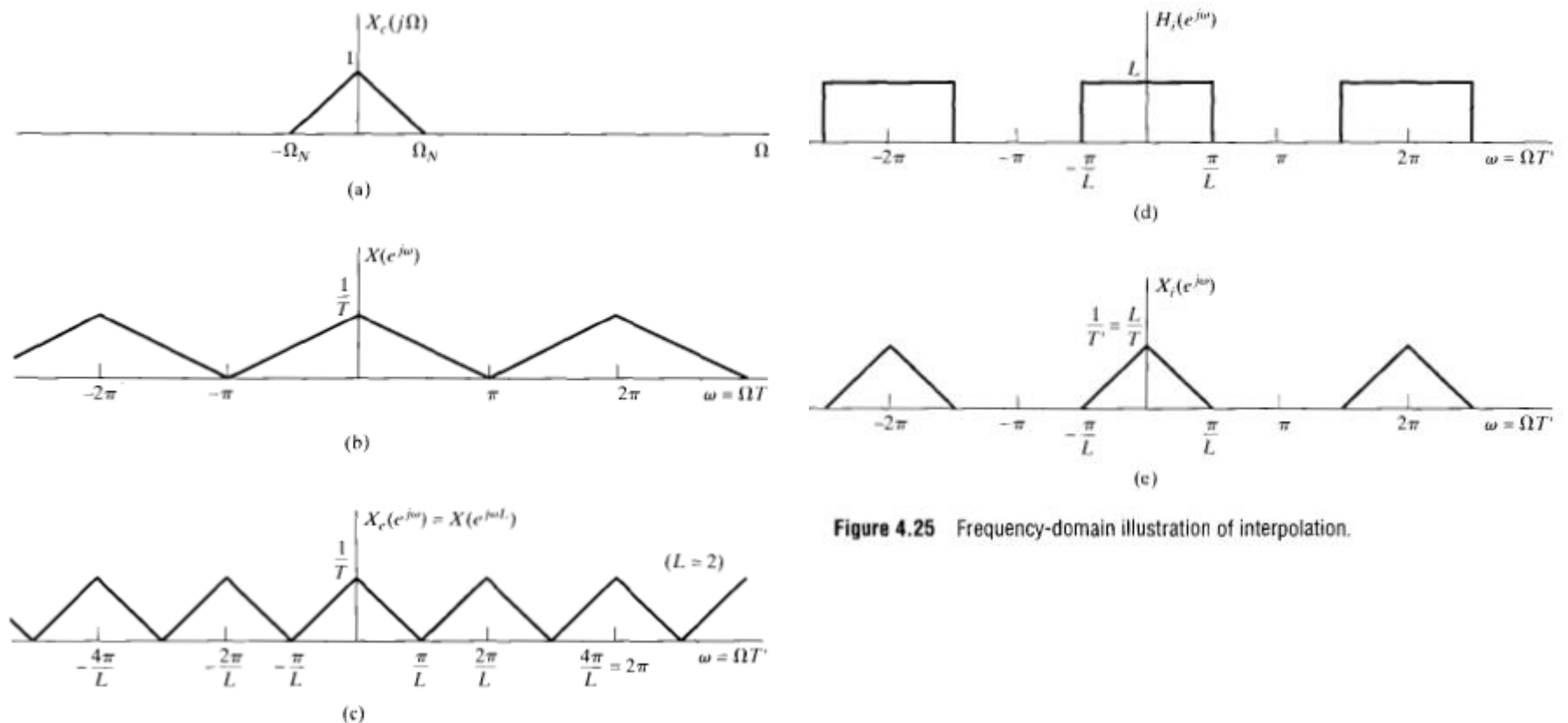


Figure 4.25 Frequency-domain illustration of interpolation.

Up-Sampling (Increasing the Sampling Rate)

Frequency Domain Representation of Up-Sampling

Interpolation Formula for $x_i[n]$ in terms of $x[n]$

$$h_i[n] = \frac{\sin\left(\frac{\pi n}{L}\right)}{\pi n}$$
$$x_i[n] = \sum_{k=-\infty}^{\infty} x[k] \frac{\sin\left(\frac{\pi(n - kL)}{L}\right)}{\frac{\pi(n - kL)}{L}}$$
$$h_1[0] = 1$$
$$h_i[n] = 0, \quad n = \pm L, \pm 2L, \dots$$

$$\frac{\sin W\pi}{\pi n} = \frac{W}{\pi} \operatorname{sinc}\left(\frac{Wn}{\pi}\right)$$
$$0 < W < \pi$$

$$X(\omega) \rightarrow \begin{cases} 1, & 0 \leq |\omega| \leq W \\ 0, & W < |\omega| \leq \pi \end{cases}$$

$X(\omega)$ periodic with period 2π

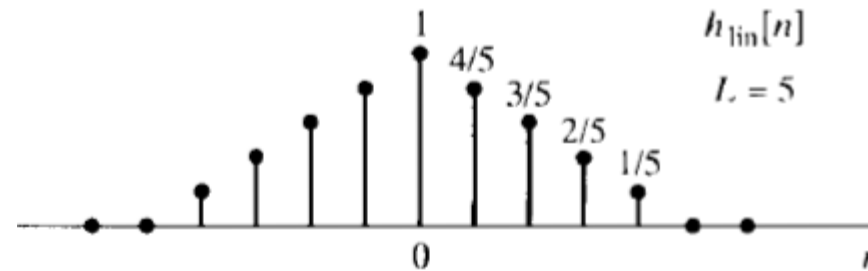
Up-Sampling (Increasing the Sampling Rate)

Frequency Domain Representation of Up-Sampling

Linear Interpolation

$$h_{lin}[n] = \begin{cases} 1 - \frac{|n|}{L}, & |n| \leq L \\ 0, & \textit{otherwise} \end{cases}$$

For $L = 5$

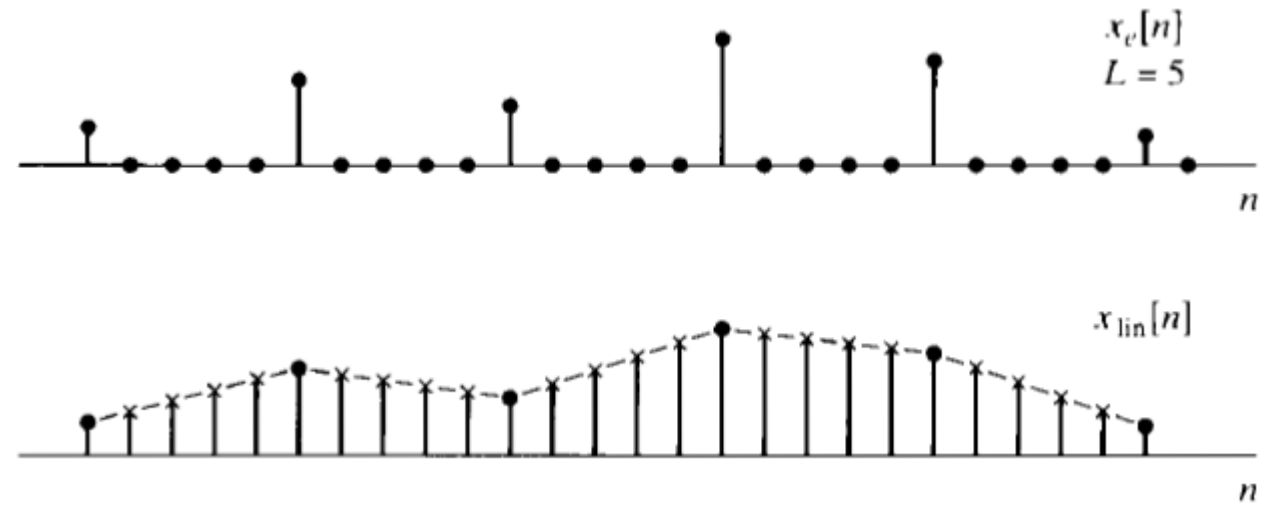


Up-Sampling (Increasing the Sampling Rate)

Frequency Domain Representation of Up-Sampling

Linear Interpolation

$$x_{lin}[n] = \sum_{k=-\infty}^{\infty} x_e[k] h_{lin}[n - k]$$
$$= \sum_{k=-\infty}^{\infty} x[k] h_{lin}[n - kL]$$

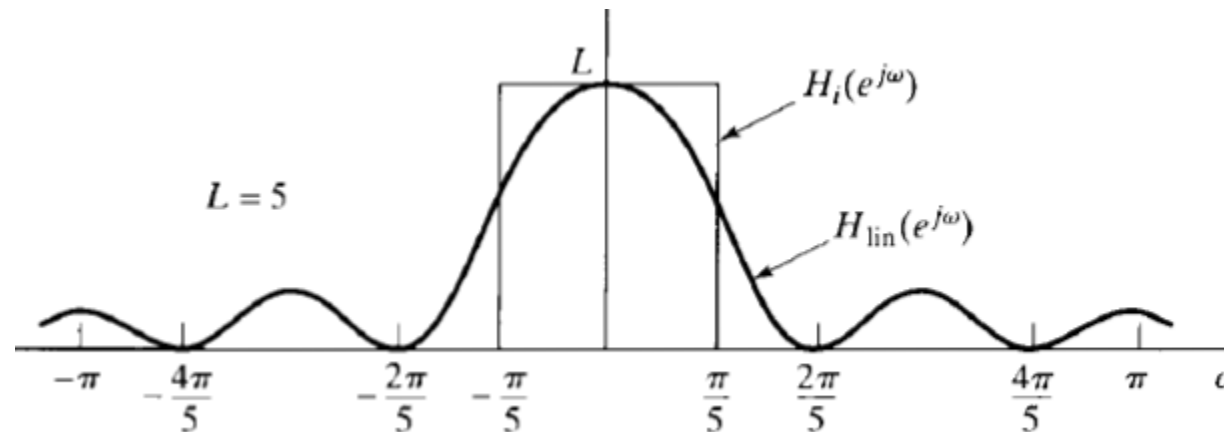


Up-Sampling (Increasing the Sampling Rate)

Frequency Domain Representation of Up-Sampling

Linear Interpolation

$$H_{lin}[e^{j\omega}] = \frac{1}{L} \left[\frac{\sin(\omega L/2)}{\sin(\omega/2)} \right]^2$$



Up-Sampling (Increasing the Sampling Rate)

Frequency Domain Representation of Up-Sampling

Linear Interpolation

- If the original signal is sampled at the Nyquist rate, linear interpolation will not be very good, since the O/P of the filter will contain considerable energy in the band $\frac{\pi}{L} < |\omega| \leq \pi$.
- If the original sampling rate is much higher than Nyquist rate, then the LI will be more successful in removing the frequency-scaled images of $X_c(j\Omega)$ at multiples of $2\pi/L$.